

# Non-standard approaches to nonparametric Bayes

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# Motivation

- In Bayesian nonparametrics, the standard approach is to
  - ▶ specify a complete probabilistic model,
  - ▶ perform fully Bayesian inference, and
  - ▶ use algorithms that are exactly correct (possibly up to MCMC error).
- However, this can take a lot of time, both in terms of computation and implementation.
- Compromising on these standard assumptions can allow for methods that are faster and easier to use, and behave similarly.
- Specifically, there can be significant advantages to using
  - ▶ partially specified models,
  - ▶ a combination of frequentist and Bayesian inference, and
  - ▶ analytical approximations to BNP models.

# Outline

- 1 Brief survey of some interesting non-standard approaches
  - Analytical approximations to BNP models
  - Hybrid Bayesian-frequentist methods
  - Partially specified models
- 2 Nonparametric Laplace approximation
  - Bayesian model checking with a nonparametric alternative
  - Group comparisons (Two-sample tests)
  - Regression with unknown error distributions

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# Analytical approximations to BNP models

- Often, we are only interested in one part of a model, and the rest is just necessary to adequately fit the data.
- Idea: Find analytical approximations for dealing with the parts we don't care about.
- Shift the burden from computation to analysis (i.e., invest more time on derivation & justification instead of running MCMC forever).

# Analytical approximations to BNP models

- Example: Recent work by Matt Taddy
  - ▶ Take some functional of interest  $\beta(P)$ , e.g., least squares linear fit.
  - ▶ Consider the posterior of  $\beta(P)$  when  $P \sim DP(\alpha, H)$  with  $\alpha \rightarrow 0$ .
  - ▶ Take a first-order Taylor approximation  $\tilde{\beta}(P) \approx \beta(P)$ , and obtain analytical expressions for posterior moments of  $\tilde{\beta}(P)$ .
- Example: C-posterior — analytical approximation to marginal likelihood under nonparametrically coarsened models.
- Example: Nonparametric Laplace approximation (this talk) — approximation to marginal likelihood under a nonparametric sieve.

# Hybrid Bayesian-frequentist methods

- There's some great stuff outside Bayesian statistics.
- Fast non-Bayesian algorithms for key problems
  - ▶ multivariate density estimation (GMRA, IFGT, Dual trees)
  - ▶ nearest neighbor search (random k-d tree, k-means tree, LSH)
  - ▶ clustering (CLIQUE, BIRCH, DBSCAN)
  - ▶ property testing with sublinear time algorithms
  - ▶ nonparametric regression, classification, dimensionality reduction, stochastic optimization, convex optimization, ensemble methods, randomized algorithms, etc., etc., etc.
- Can we combine these with Bayes, to obtain fast semi-Bayesian nonparametric methods?

# Hybrid Bayesian-frequentist methods

- Example: For conditional density estimation, Petralia, Vogelstein, and Dunson (2013) use a frequentist method to choose a multiscale partition, and combine this with a Bayesian model.
- Example: Nonparametric Laplace approximation (this talk) employs a frequentist density estimate to approximate a nonparametric Bayesian marginal likelihood.



# Partial models and generalized posteriors

- Fully Bayesian inference involves specifying a complete model.
- When little prior knowledge is available about a certain part of the model, it is common to use BNP for this part.
- In some cases, another option is to use a partially specified model in which this part is not modeled at all. This results in a loss of information, but often the loss is minimal.
- This is an old idea, but not many Bayesians seem to use it.  
“We’re Bayesians — we don’t want to lose any information!”

## Partial models and generalized posteriors

- The Neyman–Scott problem is a simple but really nice example:
- Suppose  $X_i, Y_i \sim \mathcal{N}(\mu_i, \sigma^2)$  indep. for  $i = 1, \dots, n$ , and we want to infer  $\sigma^2$ , but the distribution of the  $\mu$ 's is completely unknown.
- Problem: Prior on the  $\mu$ 's does not go away — using the wrong prior leads to inconsistency.
- Full BNP approach: put a prior on the distribution of the  $\mu$ 's, e.g., use a Dirichlet process mixture and do inference with usual algorithms.
- Partial model approach: Let  $Z_i = X_i - Y_i \sim \mathcal{N}(0, 2\sigma^2)$  and use  $p(\sigma^2 | z_1, \dots, z_n)$  to infer  $\sigma^2$ . Way easier than full BNP!
- Partial model gives consistent and correctly calibrated Bayesian posterior on  $\sigma^2$  — just slightly less concentrated.

## Partial models and generalized posteriors

- There are a variety of ways to obtain a generalized likelihood.
  - ▶ conditional likelihood, partial likelihood, pseudo-likelihood, composite likelihood, restricted/marginal likelihood, rank likelihood, etc.
- Generalized posterior  $\propto$  generalized likelihood  $\times$  prior.
- Generalized posteriors can have advantages over the standard posterior in terms of computation and robustness.
  - ▶ Doksum & Lo (1990) — Using  $p(\theta \mid \text{median}(x_{1:n}))$  fixes the Diaconis & Freedman (1986) inconsistency issue.
  - ▶ Raftery, Madigan, & Volinsky (1996)
  - ▶ Hoff (2007)
  - ▶ Liu, Bayarri, & Berger (2009)
  - ▶ Pauli, Racugno, & Ventura (2011)
  - ▶ Lewis, MacEachern, & Lee (2014)
- Main issue is ensuring correct calibration of generalized posteriors.
- In recent work, we have developed Bernstein–Von Mises results for generalized posteriors, to facilitate correct calibration.

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# Nonparametric Laplace approximation — Motivation

- A common usage of BNP models is as a prior on an unknown “nuisance” distribution.
- Examples
  - ▶ Regression with unknown error distribution(s).
  - ▶ Many parameters with a common unknown distribution (e.g., Neyman–Scott problem).
  - ▶ Nonparametric alternative for Bayesian model checking.
  - ▶ Comparing groups for equality of distribution (two-sample testing).
- In such cases, we don't care about the unknown distribution itself.
- Using something like a DPM for this is slow and tedious.
- The DP is (often) inapplicable if the data is continuous.

# Nonparametric Laplace approximation — Motivation

- It would be nice to be able to integrate out the unknown distribution and have an analytical expression for the resulting marginal likelihood.
- Polya trees (Lavine, 1992) are often used for this reason.
  - ▶ Berger & Guglielmi (2001) — Bayesian model checking
  - ▶ Hanson and Johnson (2002) — nonparametric regression error
  - ▶ Holmes, Caron, Griffin, & Stephens (2015) — two-sample testing
- However, Polya trees strongly depend on a rather arbitrary choice of partition sequence (especially in multiple dimensions). Mixtures of Polya trees are better, but require additional computation. Polya trees also tend to generate spiky distributions.
- We are working on a new approach, with the aim of developing a nonparametric analogue of the Laplace approximation.

## Nonparametric Laplace approximation

- Recall the Laplace approximation to the marginal likelihood:

$$m(x_{1:n}) = \int \left( \prod_{i=1}^n p(x_i|\theta) \right) \pi(\theta) d\theta \approx \left( \prod_{i=1}^n p(x_i|\hat{\theta}) \right) \left( \frac{2\pi}{n} \right)^{D/2} \frac{\pi(\hat{\theta})}{|H(\hat{\theta})|^{1/2}}$$

where  $\hat{\theta}$  is the MLE and  $D$  is the dimensionality of  $\theta$ .

- When  $\theta$  is infinite-dimensional, this is clearly inapplicable. However, by using a sieve (i.e., let model complexity grow with  $n$ ), perhaps we can mimic the infinite-dimensional case.
- Thus, to obtain an infinite-dimensional analogue, we consider a sieve of continuous coarsenings of  $DP(\alpha, H)$ , leading to:

$$m(x_{1:n}) \approx \left( \prod_{i=1}^n \hat{f}(x_i) \right) \left( \frac{2\pi}{n + \alpha} \right)^{\tilde{D}/2} C_n(\hat{f}, \alpha, H)$$

where  $\hat{f}(x)$  is a nonparametric density estimate and  $\tilde{D}$  is the “effective dimensionality.”

# Nonparametric Laplace approximation

- In more detail,

$$m(x_{1:n}) \approx \tilde{m}_{\text{NPL}}(x_{1:n}) = \left( \prod_{i=1}^n \hat{f}(x_i) \right) \left( \frac{2\pi}{n + \alpha} \right)^{\tilde{D}/2} C_n(\hat{f}, \alpha, H)$$

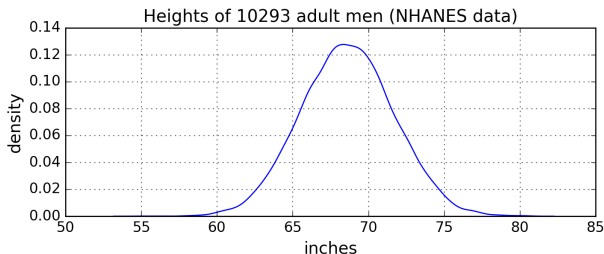
$$C_n(\hat{f}, \alpha, H) = \frac{\Gamma(\alpha)(n + \alpha)^n}{\Gamma(n + \alpha)e^n} \prod_{i=1}^n \left( \frac{(w\hat{f}(x_i)(n + \alpha)/e)^{wh(x_i)}}{\sqrt{w\hat{f}(x_i)\Gamma(wh(x_i))}} \right)^{D_i}$$

- ▶  $\hat{f}(x)$  is a nonparametric density estimate,
  - ▶  $\tilde{D} = \sum_{i=1}^n D_i$  and  $D_i = 1/(wn\hat{f}(x_i))$ ,
  - ▶  $w$  is a complexity parameter of the density estimate (e.g., bandwidth),
  - ▶  $\alpha$  is the concentration parameter, and
  - ▶  $h$  is the density of the base distribution  $H$ .
- Given a nonparametric density estimate  $\hat{f}$ , this is easy to compute.
  - It applies in the multivariate case.



## Example 1: Bayesian model checking

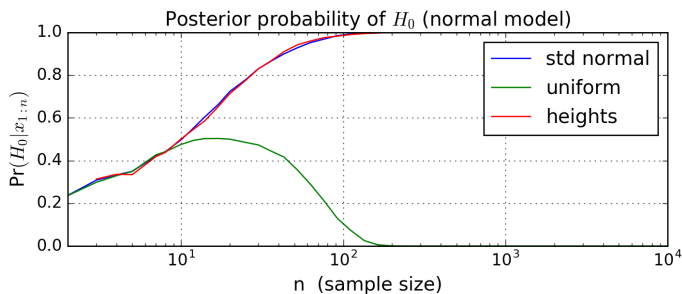
- Are human heights normally distributed? (Well, obviously not, since height is nonnegative. But how good is the normal model for my set of  $n$  datapoints?)



- $H_0$ : Normal model,  $H_1$ : Nonparametric alternative.
- $\Pr(H_0|x_{1:n}) = \left(1 + \frac{p(x_{1:n}|H_1)p(H_1)}{p(x_{1:n}|H_0)p(H_0)}\right)^{-1}$
- $p(x_{1:n}|H_0) =$  Normal–NormalGamma marginal likelihood
- $p(x_{1:n}|H_1) \approx \tilde{m}_{\text{NPL}}(x_{1:n}) =$  NP Laplace approx

## Example 1: Bayesian model checking

Results as the sample size  $n$  increases, for three different datasets:



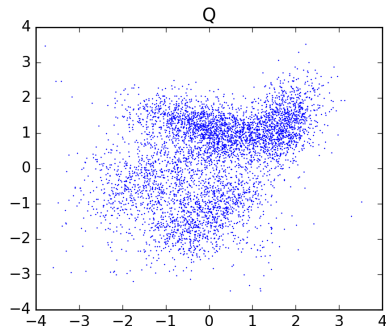
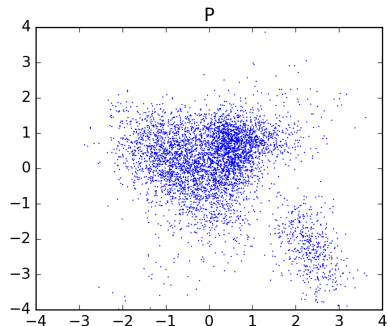
- std normal: Data is  $x_1, \dots, x_n$  i.i.d.  $\sim \mathcal{N}(0, 1)$ .
- uniform: Data is  $x_1, \dots, x_n$  i.i.d.  $\sim \text{Uniform}(-1, 1)$ .
- heights:  $x_1, \dots, x_n$  are the heights of adult men (NHANES data).  
The normal model appears to be adequate *for the given sample size*.
- (Curves shown are averaged over multiple permutations of the data.)

## Example 2: Two-sample testing (Group comparison)

- Do groups A and B have the same distribution? This question is ubiquitous in scientific and industrial applications, e.g.,
  - ▶ Does the treatment have any effect?
  - ▶ Does knocking out gene G affect disease D?
  - ▶ Does using material M affect product quality?
- Assume  $X_1, \dots, X_n | P$  i.i.d.  $\sim P$  and  $Y_1, \dots, Y_m | Q$  i.i.d.  $\sim Q$ .
- $H_0 : P = Q$ ,  $H_1 : P \neq Q$
- BNP approach: Put nonparametric priors on  $P$  and  $Q$ .
- We can approximate a nonparametric marginal likelihood using NPL.
- $p(x_{1:n}, y_{1:m} | H_0) \approx \tilde{m}_{\text{NPL}}(x_{1:n}, y_{1:m})$
- $p(x_{1:n}, y_{1:m} | H_1) = p(x_{1:n} | H_1) p(y_{1:m} | H_1) \approx \tilde{m}_{\text{NPL}}(x_{1:n}) \tilde{m}_{\text{NPL}}(y_{1:m})$

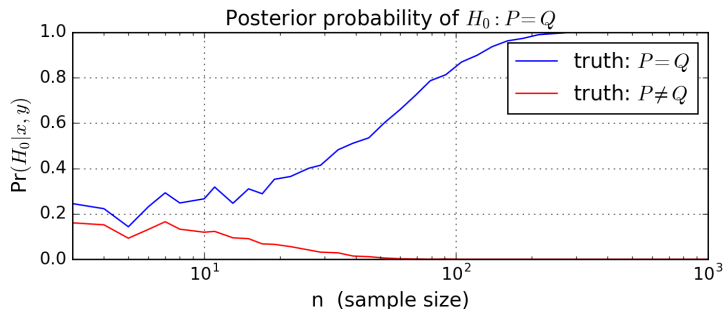
## Example 2: Two-sample testing (Group comparison)

Simulated data from two randomly-chosen normal mixtures,  $P$  and  $Q$



## Example 2: Two-sample testing (Group comparison)

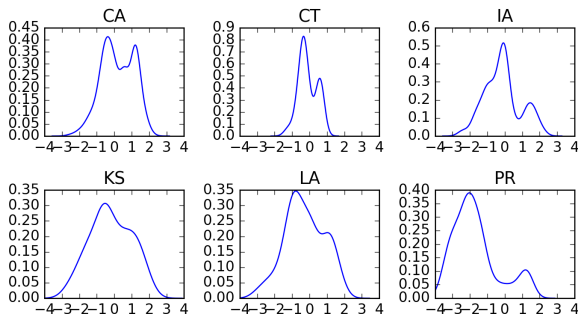
Results as the sample size  $n$  increases (averaged over multiple runs):



- When the truth is  $P = Q$ , we observe  $\widetilde{\Pr}(P = Q|x_{1:n}, y_{1:m}) \rightarrow 1$ .
- When the truth is  $P \neq Q$ , we observe  $\widetilde{\Pr}(P = Q|x_{1:n}, y_{1:m}) \rightarrow 0$ .
- The NPL approach seems to be working as expected.

## Example 3: Regression with unknown error distributions

- Consider HHS data on pneumonia treatment quality in US hospitals.
  - ▶ Covariate vector  $x_{ij} \in \mathbb{R}^p$  for each hospital  $j$  in each state  $i$ .
  - ▶  $y_{ij}$  = percent of patients given correct treatment (logit-transformed).
- Residuals from a pooled linear regression indicate non-normal errors:



- Following Rodriguez, Dunson, & Gelfand (2008), we model the error distribution for each state nonparametrically.

## Example 3: Regression with unknown error distributions

- Model:

$\beta \sim$  multivariate normal

$f_1, \dots, f_k \sim$  nonparametric prior on densities

$$p(y_{ij}|x_{ij}, \beta, f_i) = f_i(y_{ij} - \beta^T x_{ij}).$$

- Suppose we're interested in  $\beta$ , but not  $f_1, \dots, f_k$ .
- We can use NPL to construct an approximate marginal likelihood:

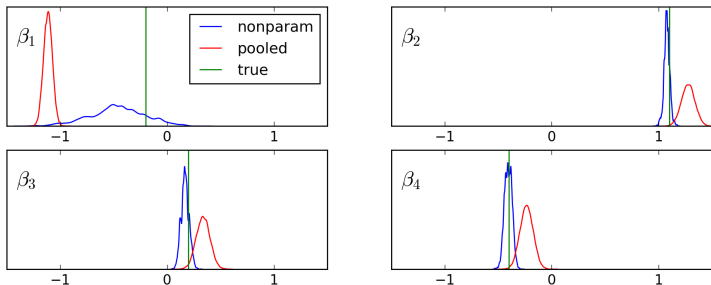
$$p(y|x, \beta) \approx \prod_{i=1}^k \tilde{m}_{\text{NPL}}(r_{i1}(\beta), \dots, r_{in_i}(\beta))$$

where  $r_{ij}(\beta) = y_{ij} - \beta^T x_{ij}$ .

- We can then run Metropolis–Hastings to sample  $\beta$ .

## Example 3: Regression with unknown error distributions

Posterior densities of the coefficients  $\beta_i$ , for simulated data

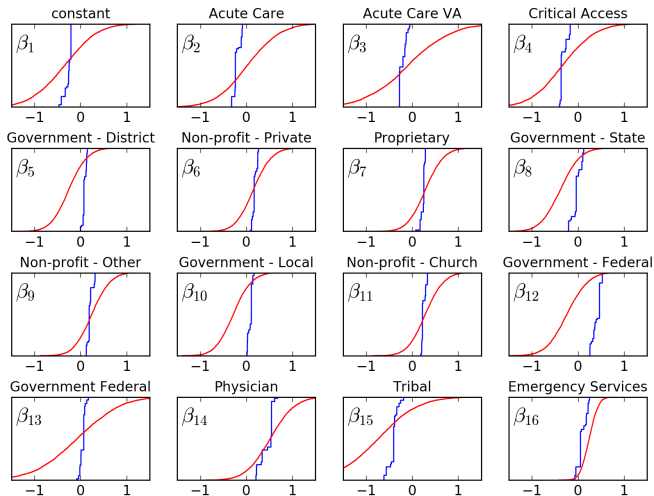


- As one might expect, a pooled linear regression model doesn't work well — the posterior on  $\beta$  is not concentrating at the true values.
- Meanwhile, the nonparametric Laplace (NPL) approach seems to work quite well — the true values are well-supported by the posterior.
- (A hierarchical normal model should be added to this comparison.)



## Example 3: Regression with unknown error distributions

CDFs for results on hospital data (blue=nonparam, red=pooled):



# Conclusion

- These preliminary results suggest that the nonparametric Laplace approximation idea is promising as a computationally-efficient alternative to a full Bayesian nonparametric marginal likelihood.
- More generally, non-standard approaches to BNP provide interesting opportunities for advances in terms of computation, ease-of-use, and robustness.

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