

Robust inference and model selection using bagged posteriors

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Slides: <http://jwmi.github.io/talks/csu2021.pdf>

Preprint 1: <https://arxiv.org/abs/1912.07104>

Preprint 2: <https://arxiv.org/abs/2007.14845>

Outline

- 1 Motivation
- 2 Background
- 3 Methodology (Bagged posteriors)
- 4 Theory
- 5 Applications
 - Variable selection
 - Phylogenetic tree inference
 - Hierarchical mixed effects logistic regression

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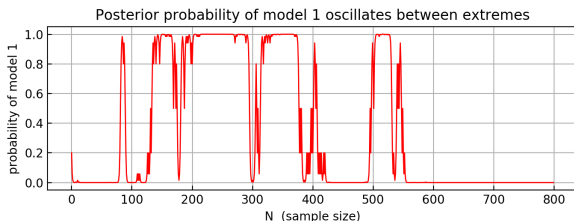
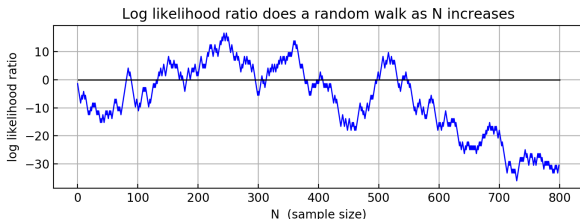
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Motivation

- Standard Bayesian inference is known to be sensitive to model misspecification.
- This leads to unreliable uncertainty quantification and poor predictive performance.
- Several methods exist for robust Bayesian inference under misspecification.
- However, finding generally applicable and computationally feasible methods is a difficult challenge.

Toy Bernoulli example

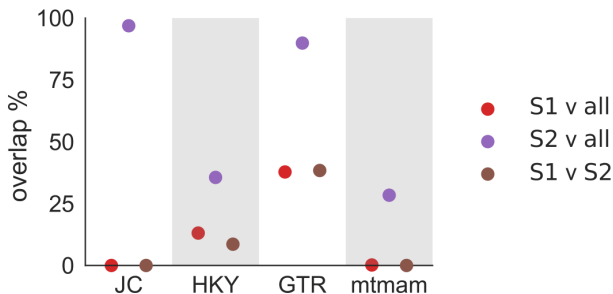
- Suppose $X_1, \dots, X_N \sim \text{Bernoulli}(p)$ i.i.d.
- Consider the (yes, contrived!) situation in which we only consider two models: (1) $p = 0.2$ and (2) $p = 0.8$, but the true value is $p = 0.501$.



Example: Phylogenetic tree inference for whale species

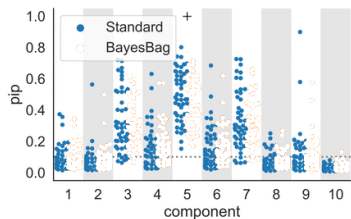
- This is not just a contrived issue – it frequently occurs in practice in phylogenetic inference.
 - ▶ Alfaro et al. (2003), Douady et al. (2003), Wilcox et al. (2002).
- Bayesian phylogenetic inference is very widely used, however, it often yields self-contradictory results due to misspecification.

Overlap between posteriors from two subsets of a whale genetics data set

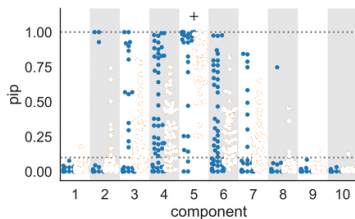


Example: Variable selection in linear regression

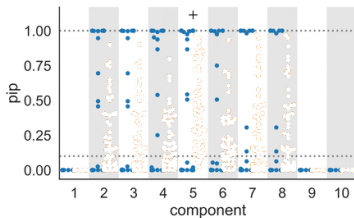
- Similarly, variable selection is unstable when there is misspecification.
- Posterior inclusion probabilities (pips) often flip-flop as N grows.



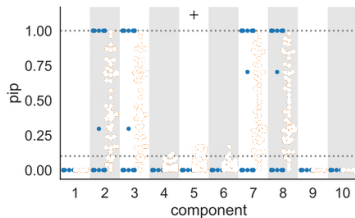
(a) $N = 5 \times 10^1$



(b) $N = 5 \times 10^2$



(c) $N = 5 \times 10^3$



(d) $N = 5 \times 10^4$

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Background

- $P_0 =$ true distribution of the observed data.
- $\{P_\theta : \theta \in \Theta\}$ is the assumed model.

- Suppose P_0 is not in the assumed model.
- The pseudo-true parameter θ^* is the nearest point to P_0 in terms of Kullback–Leibler divergence.
- In this talk, we take the usual perspective that θ^* is of interest.

- The posterior concentrates at θ^* (under regularity conditions), but ...
 - ▶ It is typically miscalibrated: credible sets do not have correct coverage.
 - ★ Kleijn & van der Vaart (2012)
 - ★ Can recalibrate using sandwich covariance (Müller, 2013, and others)

 - ▶ Slow concentration can occur, causing poor prediction performance.
 - ★ Grünwald & van Ommen (2014)
 - ★ Can fix this using a power posterior $\propto p(x|\theta)^\zeta p(\theta)$ for certain $\zeta \in (0, 1)$

Background

Many methods have been proposed for improving robustness to model misspecification.

- Fitting/prediction, focus on pseudo-true parameter θ^* .
 - ▶ Robust adjusted likelihood (Royall & Tsou, 2003)
 - ▶ SafeBayes (Grünwald & van Ommen, 2014)
 - ▶ Modular posteriors (Jacob et al., 2017)
 - ▶ Sandwich covariance adjustment (Müller, 2013)
 - ▶ Holmes & Walker (2017)
 - ... and many others.
- Inference/understanding, focus on ideal parameter θ_I .
 - ▶ Coarsened posterior (M. & Dunson, 2019)
 - ▶ Nonparametric perturbation models (M., forthcoming)

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Bagged posterior (BayesBag)

- Basic idea: Use bagging on the posterior, that is, average the posterior over many bootstrapped datasets.
- More precisely:
 - ▶ Original data set: $x = (x_1, \dots, x_N)$.
 - ▶ Bootstrapped copy of original data set: $x^* = (x_1^*, \dots, x_M^*)$.
 - ▶ Posterior obtained by treating x^* as the original data set:

$$\pi(\theta | x^*) \propto \pi_0(\theta) \prod_{m=1}^M p_{\theta}(x_m^*).$$

- ▶ The *bagged posterior* is defined by averaging these posteriors:

$$\pi^*(\theta | x) := \frac{1}{NM} \sum_{x^*} \pi(\theta | x^*),$$

where the sum is over all N^M possible bootstrap datasets of M samples drawn with replacement from the original dataset.

Bagged posterior (BayesBag): Practical considerations

- In practice, we approximate $\pi^*(\theta | x)$ by generating B bootstrap datasets $x_{(1)}^*, \dots, x_{(B)}^*$ and forming the simple Monte Carlo approximation

$$\pi^*(\theta | x) \approx \frac{1}{B} \sum_{b=1}^B \pi(\theta | x_{(b)}^*).$$

- Any posterior computation technique for the standard posterior can be used to compute each term $\pi(\theta | x_{(b)}^*)$.
 - ▶ For example, a closed-form solution, MCMC, or quadrature.
- How to choose the number of bootstrap datasets B ?
 - ▶ As a default, $B \approx 50$ to 100 often suffices.
 - ▶ Formally, the Monte Carlo error can easily be estimated, since the bootstrap datasets $x_{(b)}^*$ are i.i.d. given the original dataset.

Bagged posterior (BayesBag): Practical considerations

- How to choose the bootstrap dataset size M ?
 - ▶ The choice of M is connected to calibration of uncertainty.
 - ▶ As M/N increases, the bagged posterior becomes more concentrated.
- Recommended choice of M for model selection:
 - ▶ Our theory suggests choosing $M = o(N)$ or $M = cN$ with $c \in (0, 1]$.
 - ▶ As a default, $M = N^{0.95}$ works well in theory and practice.
 - ▶ When M/N is large, the bagged posterior behaves like the standard posterior.
- Recommended choice of M for parameter inference:
 - ▶ As a default, $M = N$ is a conservative choice that is robust to misspecification.
 - ▶ If the model is correct, then $M = 2N$ coincides with the standard posterior, asymptotically.

Previous work on bagged posteriors (BayesBag)

- Suggested by Waddell et al. (2002) and Douady et al. (2003).
 - ▶ Limited empirical study of BayesBag on phylogenetic inference.
- Independently proposed by Bühlmann (2014).
 - ▶ Limited empirical/theoretical study on a simple univariate Gaussian location model.
 - ▶ Coined the name “BayesBag”, which we adopt here.
- Surprisingly, there seems to have been little empirical or theoretical investigation of bagged posteriors.
- Bagging the posterior is very different than Bayesian Bagging (Clyde & Lee, 2001) and the Bayesian Bootstrap (Rubin, 1981), which are Bayesian ways of doing bagging and bootstrap, respectively.

Principled justification via Jeffrey conditionalization

- Jeffrey conditionalization (Diaconis & Zabell, 1982; Jeffrey, 1968):
 - ▶ Assume we have a model $p(x, y)$ for some variables x and y .
 - ▶ Suppose we are informed that $p_0(x)$ is the true distribution of x .
 - ▶ Then, Jeffrey says to quantify uncertainty in y using

$$q(y) := \int p(y|x)p_0(x)dx.$$

- Now, to connect this to the bagged posterior:
 - ▶ Take $x = x_{1:N}$ and $y = \theta$.
 - ▶ If we are informed that the true distribution is $p_0^{(N)}(x_{1:N})$, then

$$q(\theta) := \int p(\theta | x_{1:N})p_0^{(N)}(x_{1:N})dx_{1:N}.$$

- ▶ Plugging in the empirical distribution $\frac{1}{N} \sum_{i=1}^N \delta_{x_i}$ for p_0 , we obtain

$$q(\theta) \approx \frac{1}{N^N} \sum_{x_{1:N}^*} p(\theta | x_{1:N}^*),$$

which is precisely the bagged posterior with $M = N$.

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Overview of theoretical results

- We consider the setting of i.i.d. data $X_1, \dots, X_N \sim P_0$.
- **Model selection.** We show that if two models provide a nearly equally good fit to the data distribution P_0 , then:
 - ▶ the standard posterior oscillates randomly, strongly favoring one model or the other at random.
 - ▶ the bagged posterior stabilizes the probabilities probabilities of the two models, improving reproducibility.
- **Parameter inference.** We derive the mean and covariance of the bagged posterior, and prove a Bernstein–von Mises result characterizing the asymptotic normal distribution.

Theoretical results: Model selection

- Asymptotically, we know the posterior concentrates on the model that is nearest in Kullback–Leibler (KL) divergence to the true distribution.
- To study the non-asymptotic regime via an asymptotic analysis, we consider sequences of models $\mathbf{m}_{1,N}$ and $\mathbf{m}_{2,N}$.
- Letting $\Lambda_N = \log \frac{p(X_{1:N}|\mathbf{m}_{1,N})}{p(X_{1:N}|\mathbf{m}_{2,N})}$ (the log-likelihood ratio), suppose:
 - ① $\mathbf{m}_{1,N}$ and $\mathbf{m}_{2,N}$ are asymptotically comparable in the sense that

$$\lim_{N \rightarrow \infty} E_{P_0}(\Lambda_N/\sqrt{N}) = \mu_\infty \in \mathbb{R},$$

- ② $\text{Var}_{P_0}(\Lambda_N/\sqrt{N}) = \sigma_\infty^2 \in (0, \infty)$ for all N , and
 - ③ $M/N \rightarrow c \in [0, \infty)$ as $N \rightarrow \infty$, where $M = M(N) \rightarrow \infty$.
- The effect size μ_∞/σ_∞ is the evidence in favor of model 1.

Theoretical results: Model selection

- Then as $N \rightarrow \infty$, the standard posterior probability of model 1 concentrates at 0 and 1, that is, it converges to a Bernoulli r.v.:

$$\pi(\mathbf{m}_{1,N} \mid X_{1:N}) \xrightarrow{D} \text{Bernoulli}(\Phi(\mu_\infty/\sigma_\infty)).$$

- The bagged posterior probability of model 1 converges to a r.v.:

$$\pi^*(\mathbf{m}_{1,N} \mid X_{1:N}) \xrightarrow{D} \Phi(c^{1/2}Z)$$

where $Z \sim \mathcal{N}(\mu_\infty/\sigma_\infty, 1)$.

- In particular, if $\mu_\infty = 0$ and $c > 0$, then

$$\pi(\mathbf{m}_{1,N} \mid X_{1:N}) \xrightarrow{D} \text{Bernoulli}(1/2)$$

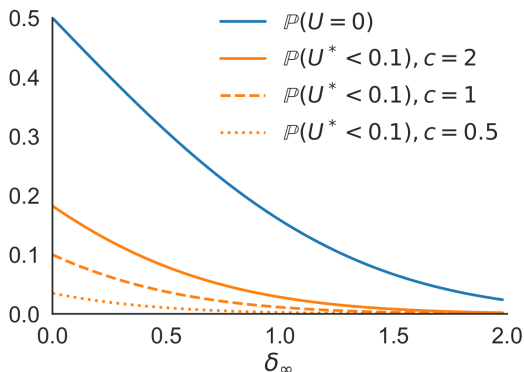
$$\pi^*(\mathbf{m}_{1,N} \mid X_{1:N}) \xrightarrow{D} \text{Uniform}(0, 1).$$

- Meanwhile, if $c = 0$ then

$$\pi^*(\mathbf{m}_{1,N} \mid X_{1:N}) \xrightarrow{D} 1/2.$$

Theoretical results: Model selection

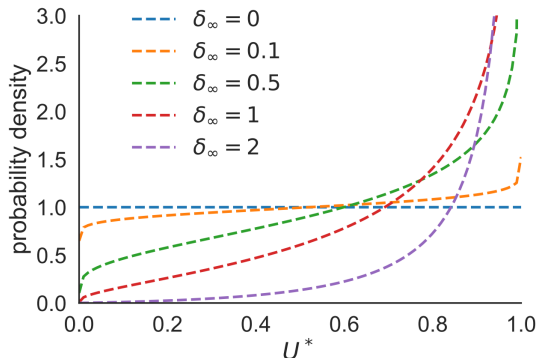
The standard posterior overwhelmingly favors the wrong model with non-negligible probability. The bagged posterior does much better.



- Standard posterior probability of model 1 converges to U .
- Bagged posterior probability of model 1 converges to U^* .
- $\delta_\infty := \mu_\infty / \sigma_\infty =$ mean effect size in favor of model 1.

Theoretical results: Model selection

The bagged posterior converges to a continuous r.v. U^* on $[0, 1]$, avoiding misleading extreme probabilities close to 0 or 1. (Shown: $c = 1$.)

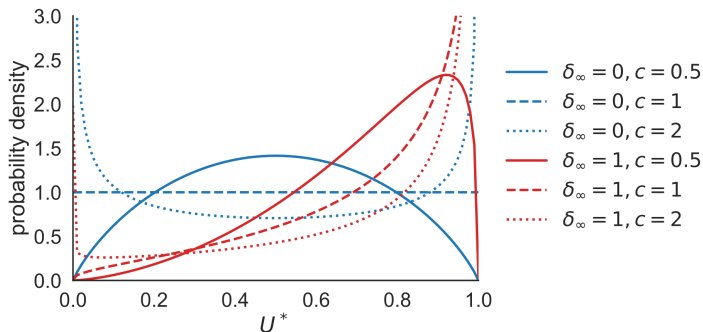


$$U^* = \Phi(c^{1/2}Z) \text{ where } Z \sim \mathcal{N}(\mu_\infty/\sigma_\infty, 1)$$

- $\delta_\infty := \mu_\infty/\sigma_\infty =$ mean effect size in favor of model 1.

Theoretical results: Model selection

Choosing M smaller makes the bagged posterior tend to be more uniform over the set of plausible models.



- $c = \lim_{N \rightarrow \infty} M/N$, where $M = M(N)$.
 - ▶ For instance, $c \in \{0.5, 1, 2\}$ when $M \in \{0.5N, N, 2N\}$, respectively.
- $\delta_\infty := \mu_\infty / \sigma_\infty =$ mean effect size in favor of model 1.

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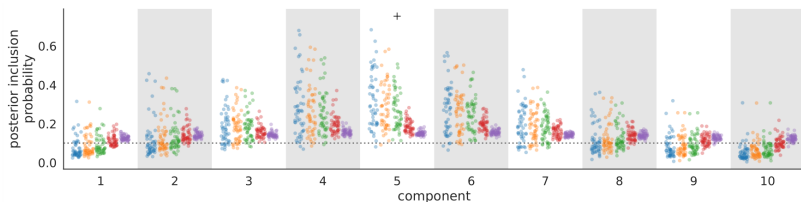
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Application: Variable selection

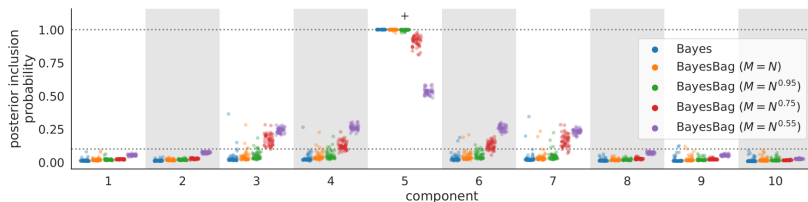
- We consider a standard Bayesian variable selection model for linear regression.
- Specifically, under the prior, each variable is included with probability q_0 , independently, and we integrate out Normal and InverseGamma priors on the coefficients and variance, respectively.
- First, we simulate datasets from (1) the assumed model and (2) a model with nonlinearly transformed covariates.
- In both scenarios, the true coefficient vector is sparse.
- We consider using $M = N^\alpha$ for $\alpha \in \{1, 0.95, 0.75, 0.55\}$ to compute the bagged posterior.

Application: Variable selection

When the model is correct, the bagged posterior with $M = N^\alpha$ is similar to the standard posterior when $\alpha = 1$ and more stable as α decreases.



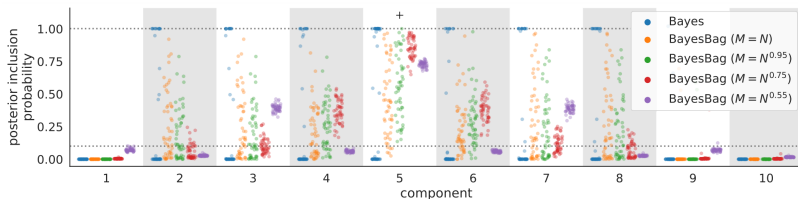
1-sparse-linear, $N = 5 \times 10^1$



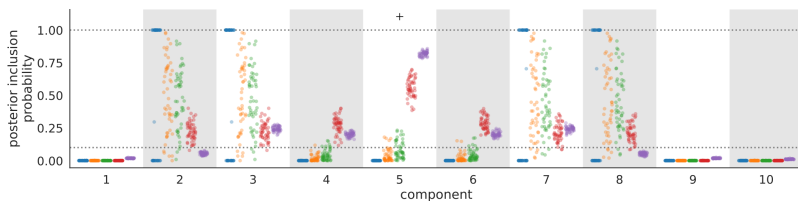
1-sparse-linear, $N = 5 \times 10^3$

Application: Variable selection

When the model is incorrect, the bagged posterior avoids the self-contradictory results produced by the standard posterior.



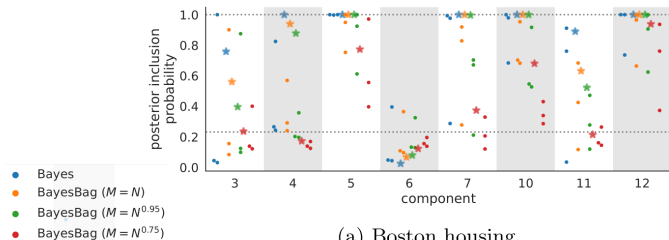
$$N = 5 \times 10^3$$



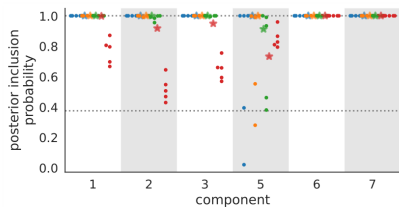
$$N = 5 \times 10^4$$

Application: Variable selection

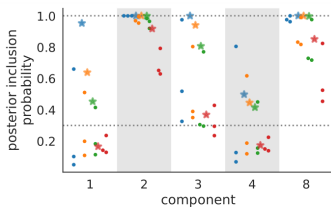
On real datasets, the bagged posterior yields greater reproducibility across subsets of the data.



(a) Boston housing



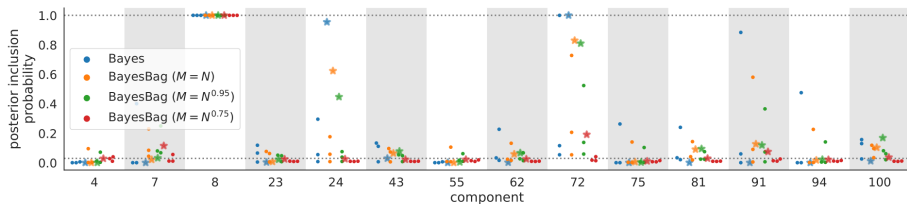
(b) California housing



(c) Diabetes

Application: Variable selection

On real datasets, the bagged posterior yields greater reproducibility across subsets of the data.

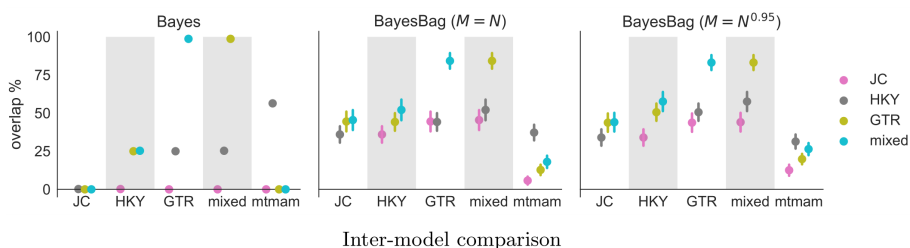


(d) Residential building

Application: Phylogenetic tree inference

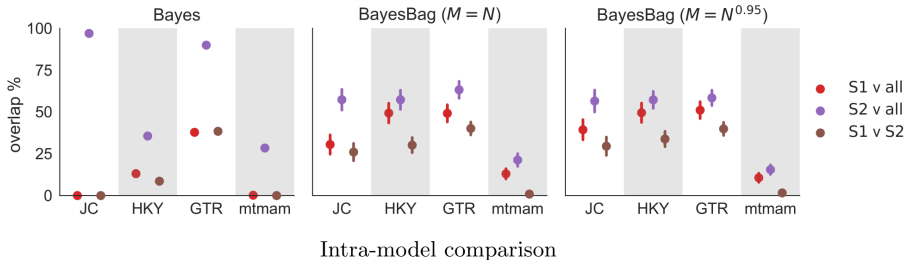
- We use a standard Bayesian package for phylogenetic inference (MrBayes 3.2, Ronquist et al., 2012).
- We used the whale dataset from Yang (2008), consisting of mitochondrial DNA from 13 whale species.
- To compute the posterior on trees, MrBayes was run using five different models for the evolutionary process (JC, HKY, GTR, mixed, and mtmam).
- For the bagged posterior, we used $M \in \{N, N^{0.95}\}$ and $B = 100$.
- To assess reproducibility, we computed the overlap of 99% highest posterior density regions for selected pairs of posteriors.

Application: Phylogenetic tree inference



- First, we consider the posterior overlap for each pair of evolutionary models.
- The standard posteriors sometimes have extremely low overlap, suggesting poor reproducibility.
- Meanwhile, the bagged posteriors exhibit more reasonable overlaps for each pair.

Application: Phylogenetic tree inference



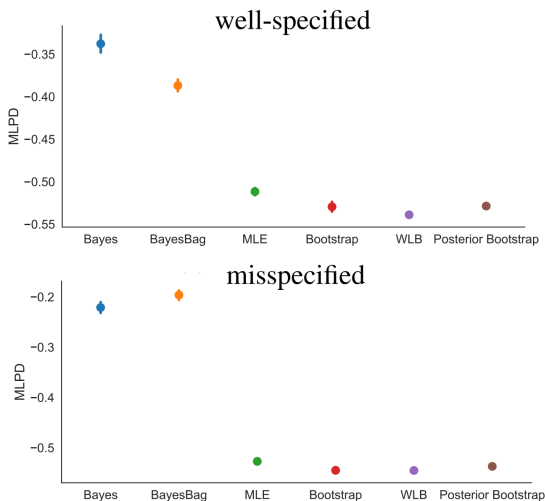
- Then, we split the genetic data into two parts, and compute the overlap for (1) the posteriors of the two splits, and (2) the posteriors for each split and the full data.
- Again, the standard posterior exhibits poor reproducibility, while the bagged posterior is more self-consistent.

Application: Hierarchical mixed effects logistic regression

- Finally, we consider a mixed effects model from Browne and Draper (2006), applied to prenatal care data from Guatemalan communities.
- We compare the predictive performance of the standard posterior, the bagged posterior, and four methods based on maximum likelihood estimation (with the random effects integrated out):
 - ▶ the standard MLE,
 - ▶ the bootstrapped MLE,
 - ▶ the weighted likelihood bootstrap (Newton and Raftery, 1994), and
 - ▶ the posterior bootstrap (Lyddon, Walker and Holmes, 2018).

Application: Hierarchical mixed effects logistic regression

The bagged posterior performs favorably compared to the other methods in terms of mean log predictive density (MLPD).



Conclusion

- Bagging the posterior is an easy-to-use and widely applicable method that improves upon standard Bayesian inference by making it more stable, accurate, and reproducible.
- Directions for future work or improvements:
 - ▶ Extensions to non-i.i.d. settings such as time-series and spatial data.
 - ▶ Improved computation of bagged posteriors.
 - ▶ Finite-sample theory for bagged posteriors.
 - ▶ Improved model assessment/criticism techniques and theory.

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